

Nonlinear Multi-directional Real-time Hybrid Simulation of Rolling Pendulum Isolation Systems

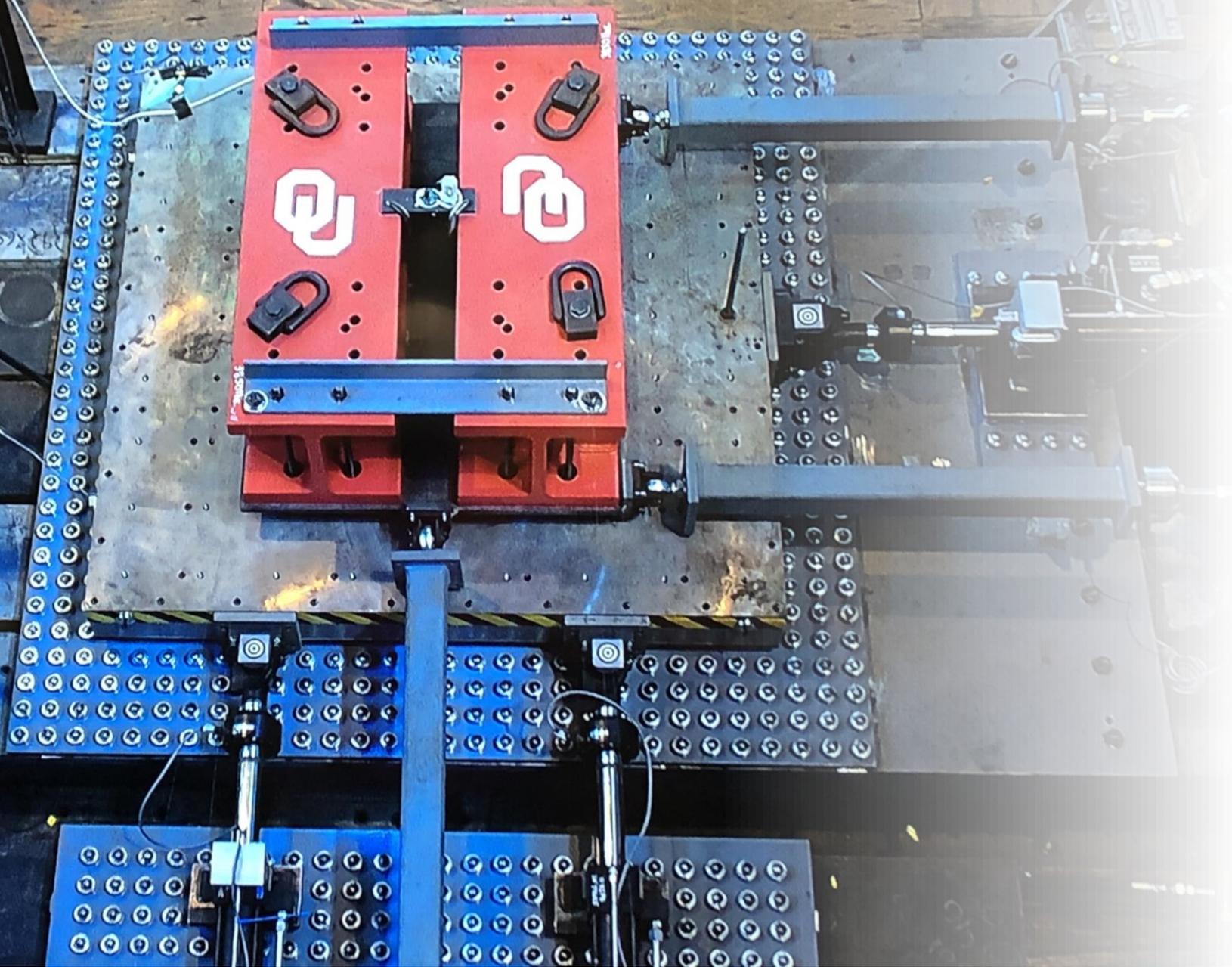
NHERI Lehigh Researcher's Workshop
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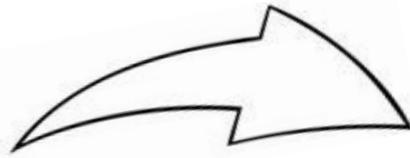




Introduction



Damage to structures due to earthquakes



Vulnerable non-structural building contents¹

Hospital equipment



(a)

<https://dir.indiamart.com/impcat/crash-cart.html>

Warehouse shelving



(b)

<https://www.shelving.com/Teardrop-Pallet-Rack-Starter-Units-p/ir3su36144-p.htm>

Valuable artwork



(c)

<https://quatr.us/greeks/classical-sculpture-ancient-greece.htm>

Network cabinet

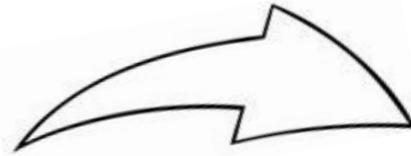


(d)

<https://www.cdw.com/shop/products/PANDUIT-NET-ACCESS-N-TYPE-CABINETS/2898087.aspx>

¹Casey, Corey D., *Rolling-Type Isolation: An Experimental Characterization and Numerical Parametric Study*, Masters Thesis, University of Oklahoma, 2017.

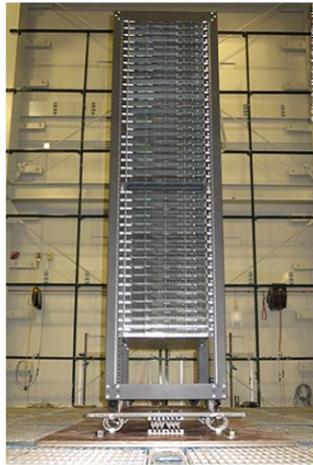
Damage to non-structural components^{2,3}



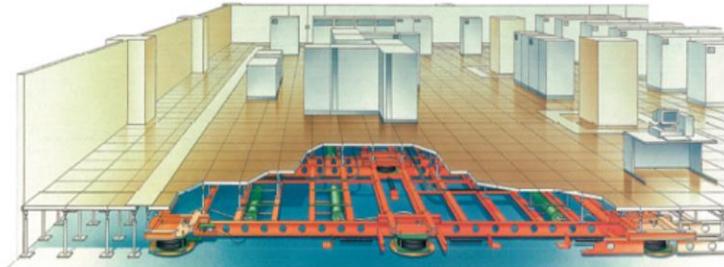
²WorkSafe Technologies, Inc., RISK VS ROI, Online, URL <https://worksafetech.com/risk-vs-roi/>, 2021.

³WorkSafe Technologies, Inc., PROJECT GALLERY, Online, URL <https://worksafetech.com/resources/product-gallery/>, 2021.

Seismic Isolation



Marin-Artieda *et al.*!



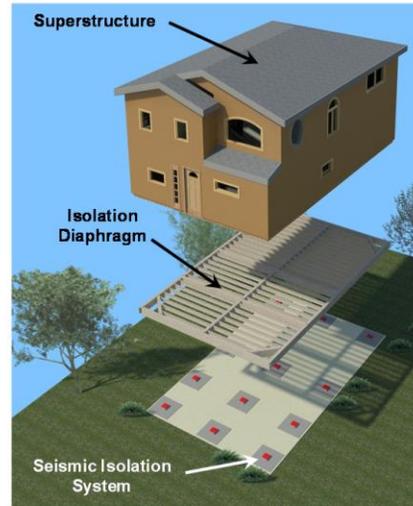
IHI (https://www.ihl.co.jp/iis/english/products/damper_floor.html)!



Buckle *et al.*!



Harvey & Song!



Deierlein *et al.*!



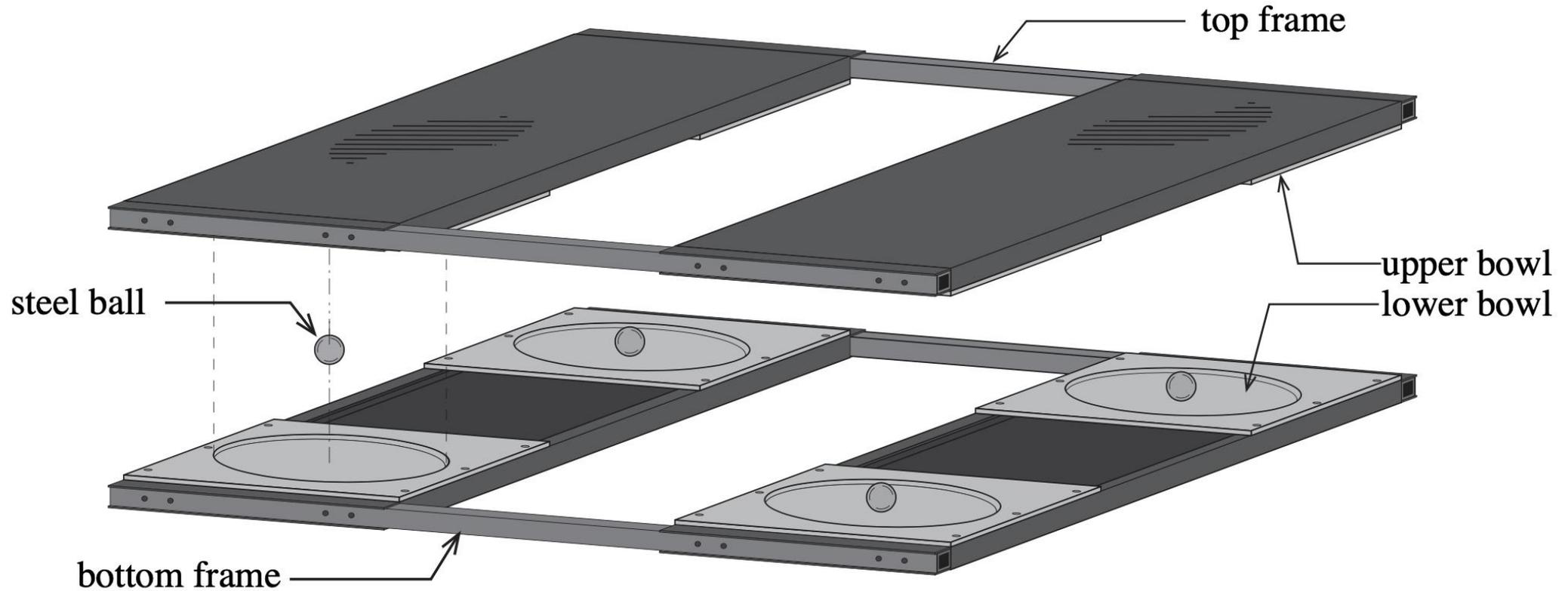
Ryan *et al.*!

Light ($\sim 10^1$ kN)!

Moderate ($\sim 10^2$ kN)!

Heavy ($\sim 10^3$ kN)!

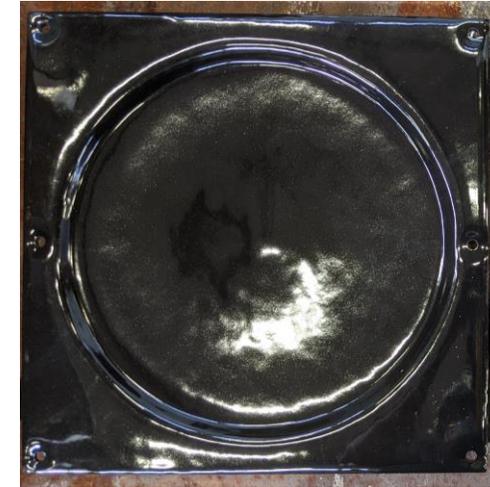
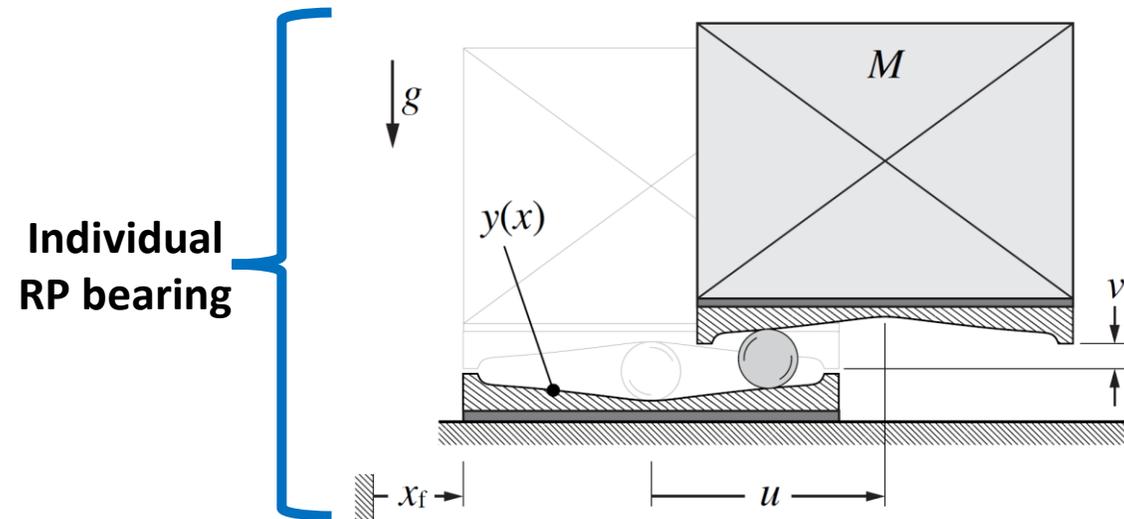
Rolling Pendulum (RP) bearing⁴



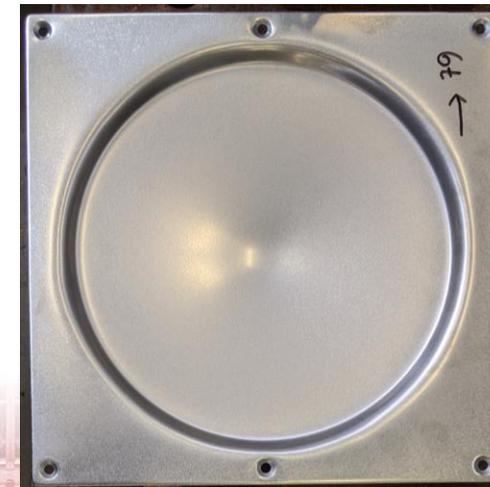
Single cabinet configuration

⁴Casey, C.D., Harvey Jr., P.S. & Song, Journal of Earthquake Engineering. doi: 10.1016/j.engstruct.2018.06.118

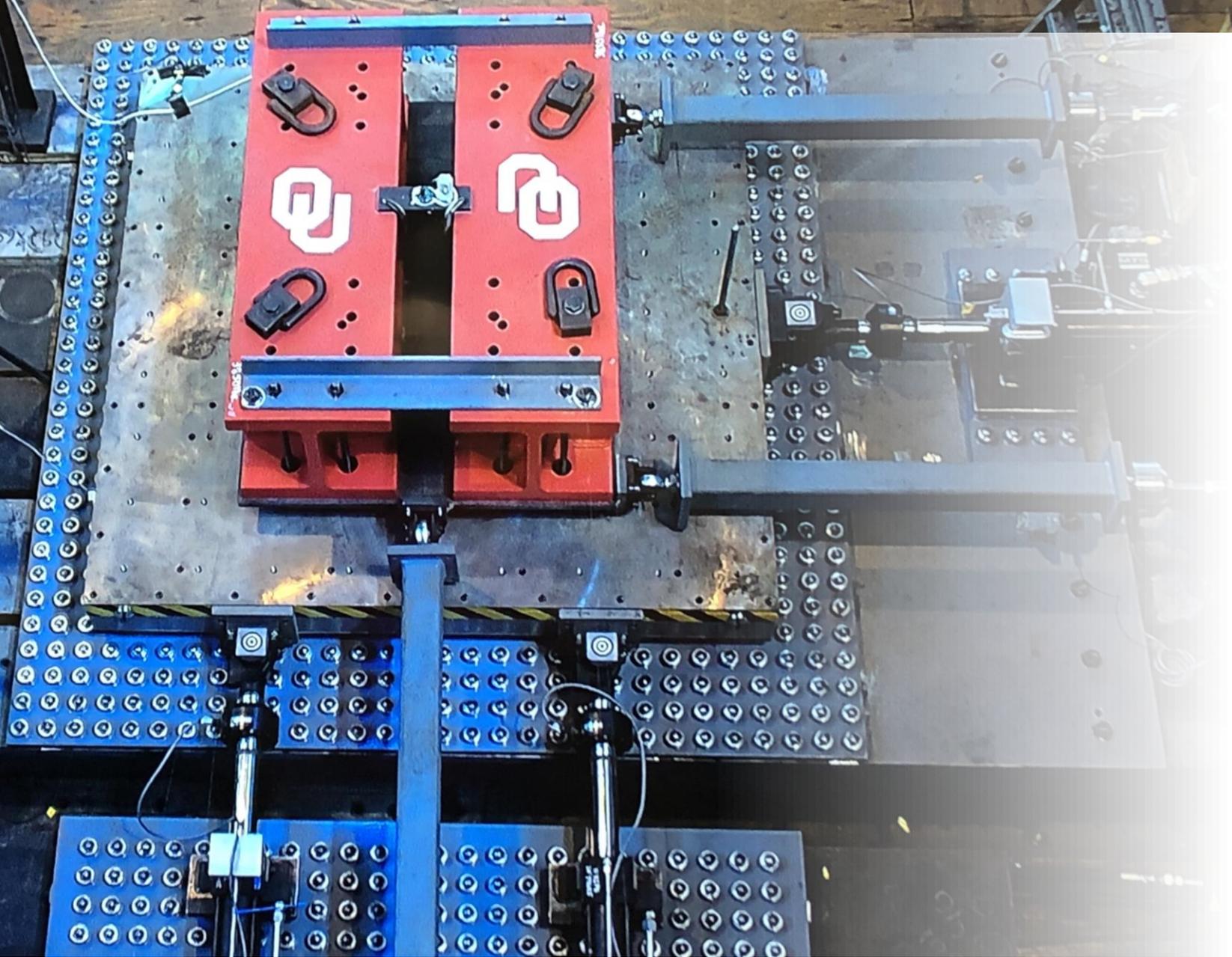
Rolling Pendulum (RP) bearing (cont.)



Coated (QuakeCoat™)



Uncoated



Test set-up

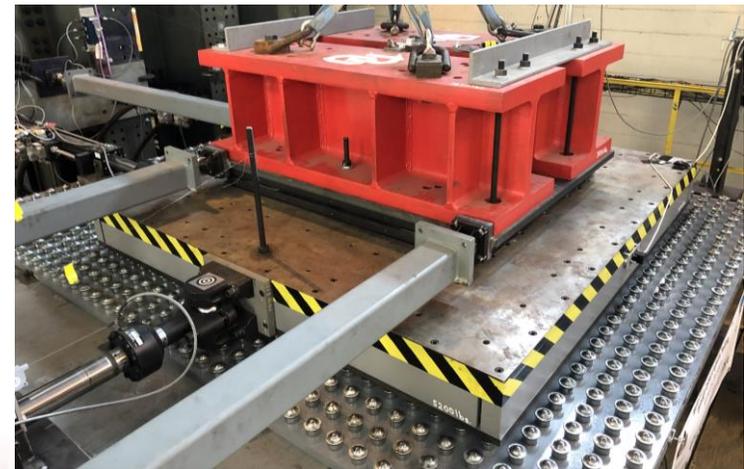


Test set-up

- Single full-scale OCTO-Base™ isolation system (4 RP bearings) from WorkSafe™ Technologies (coated and uncoated)
- Shake table NHERI Lehigh EF is mounted on top of a roller bearing bed and free to move and rotate in the plane (X, Y, θ) by means of 3 actuators



South-West top general view



North-East view

Test set-up

- Bottom component of the isolation system is attached to the shake table
- Attached atop: assembly composed of I-beams and a transfer plate, which represents the tributary weight of 17.9 kN (3,850 lb)

Top isolation system + Tributary weight



Top isolation system restraints

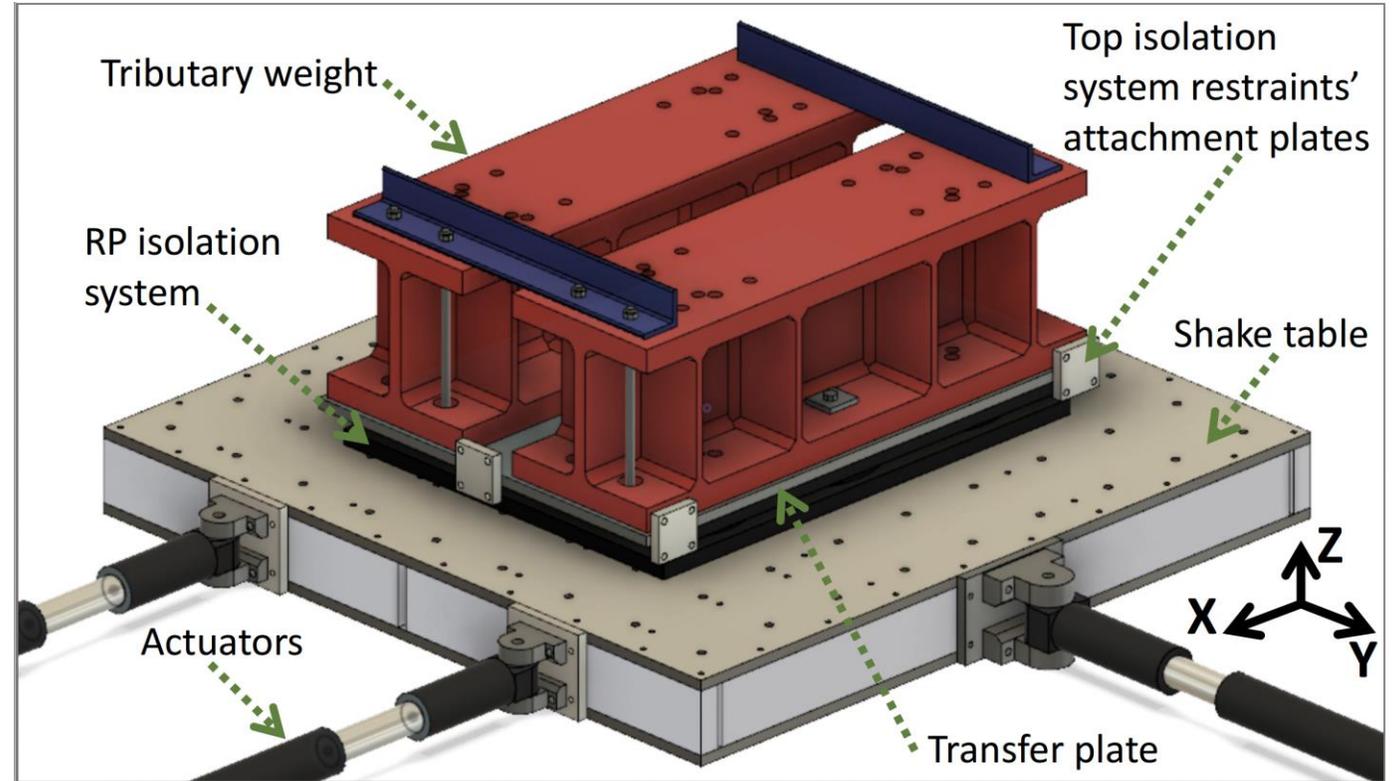
Bottom isolation system

North view

(handling top components)

Test set-up (cont.)

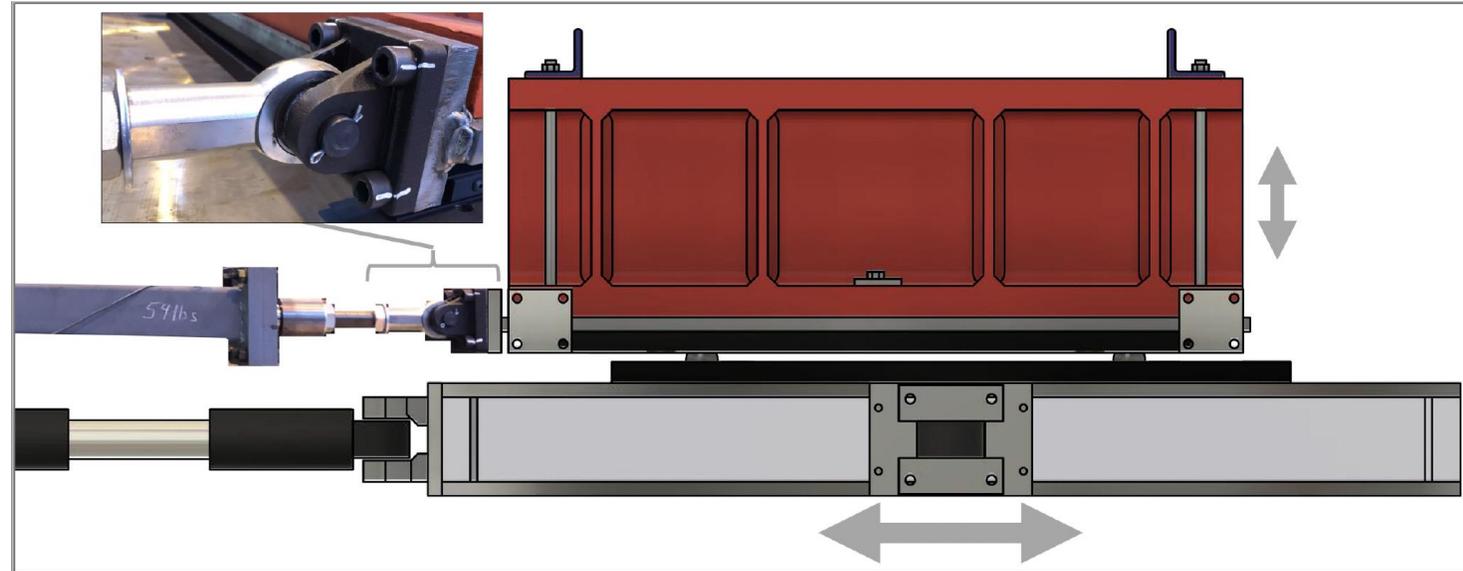
- Top component is restricted from any horizontal movement or rotation by means of 3 restraints attached to the transfer plate



South-East schematic view

Test set-up (cont.)

- Restraints pinned at both ends
- Uniaxial load cells located at the restraints to obtain directly the experimental restoring force

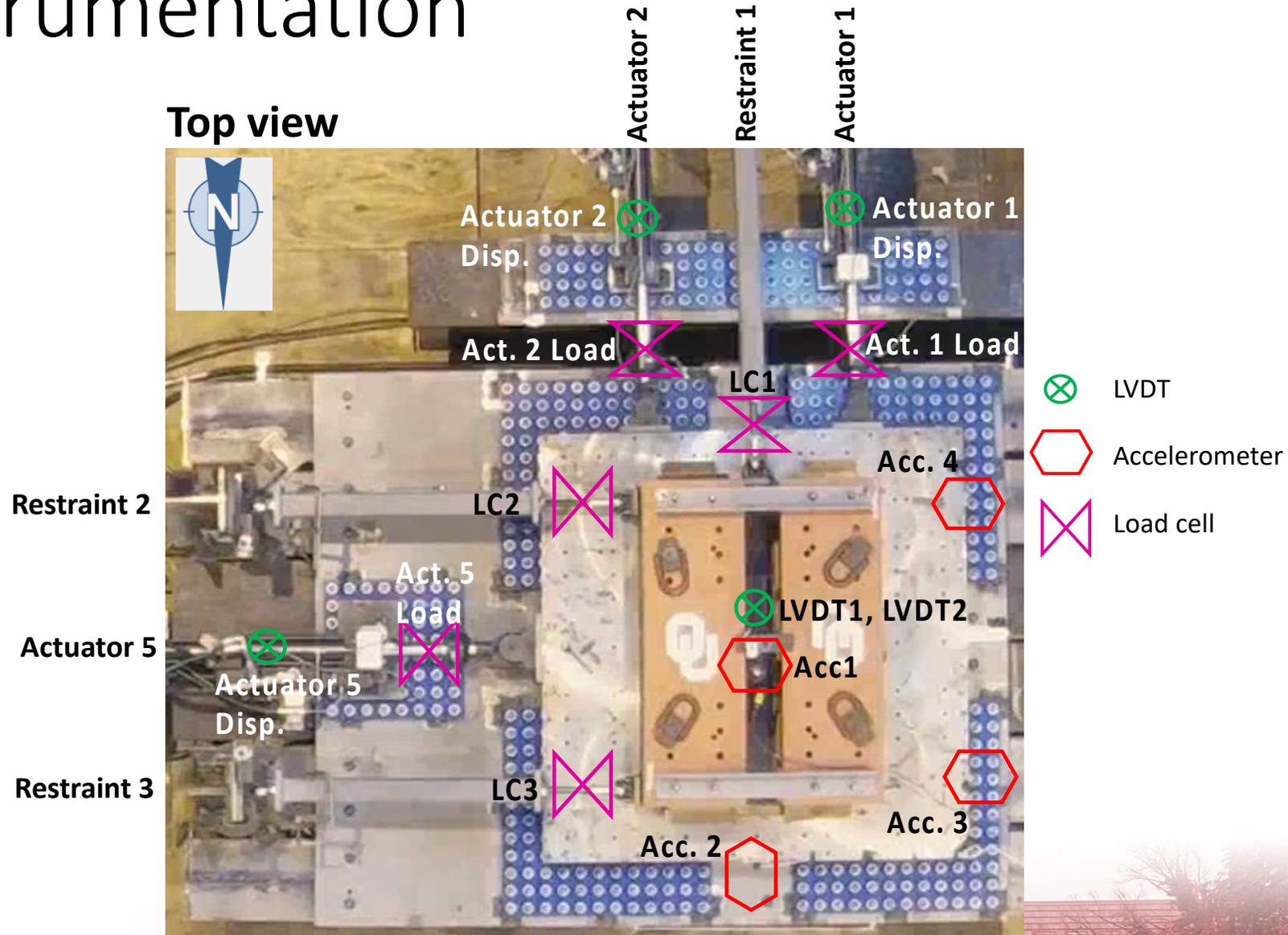


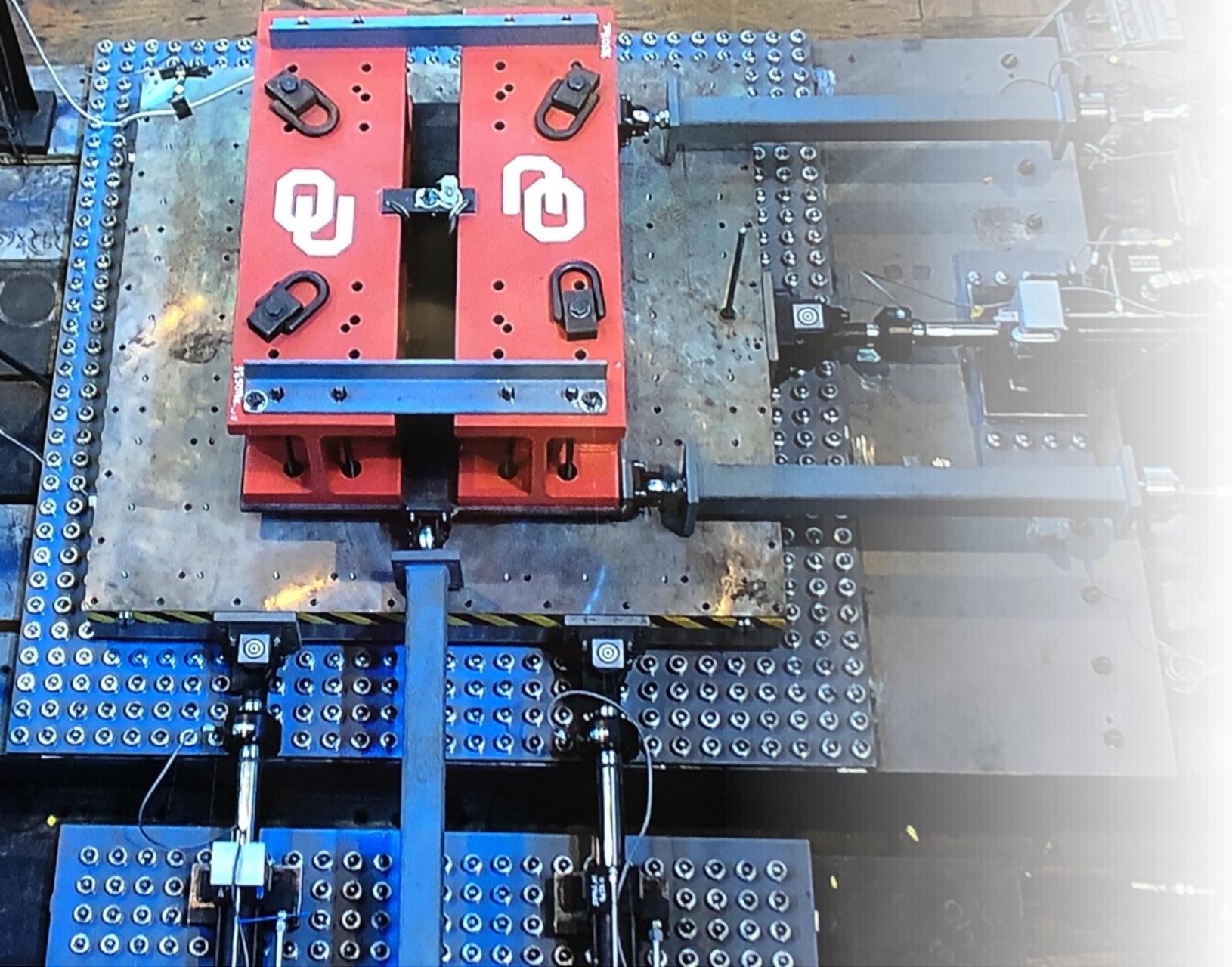
East schematic view of restraints

Test set-up: Instrumentation

- Load cells on each actuator and restraint
- Accelerometers on shake table
- LVDTs to measure the horizontal position of the shake table
- Accelerometer and LVDTs to measure the vertical motion on top of the isolation system

Top view



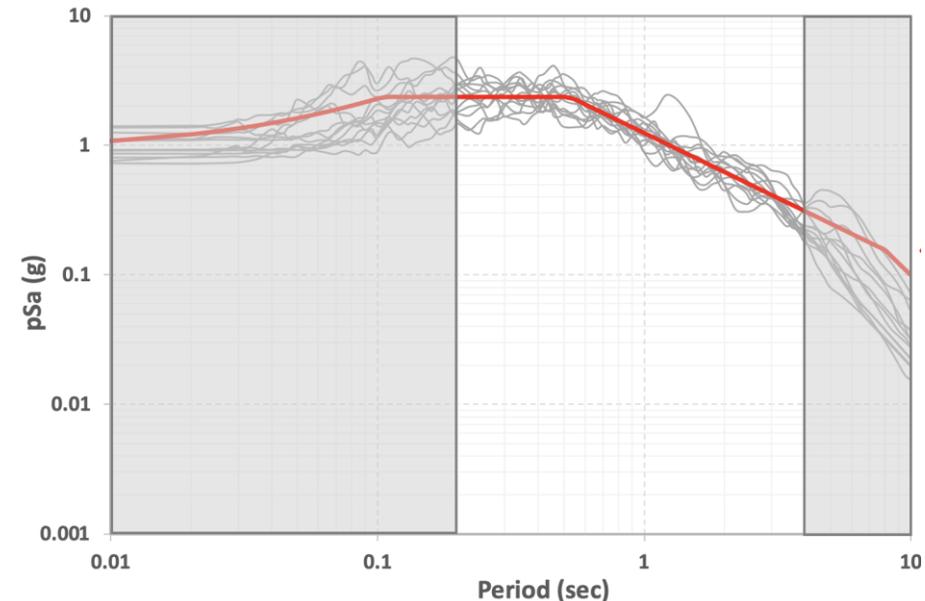


Real-time hybrid simulation



Set of earthquake records

- ASCE 7-22 Section 16.2 approach for nonlinear response history analysis:
 - Target, 5%-damped, MCE_R response spectrum was defined for the Los Angeles financial district⁵
 - Deaggregation analysis of the location showed that even though far-field controls FOE hazard, DBE and MCE are controlled by the near-fault events⁶
 - Use of the NGA-West2 database and online tool for amplitude scaling⁷



**MCE_R target response spectrum
(near-field without pulse)**

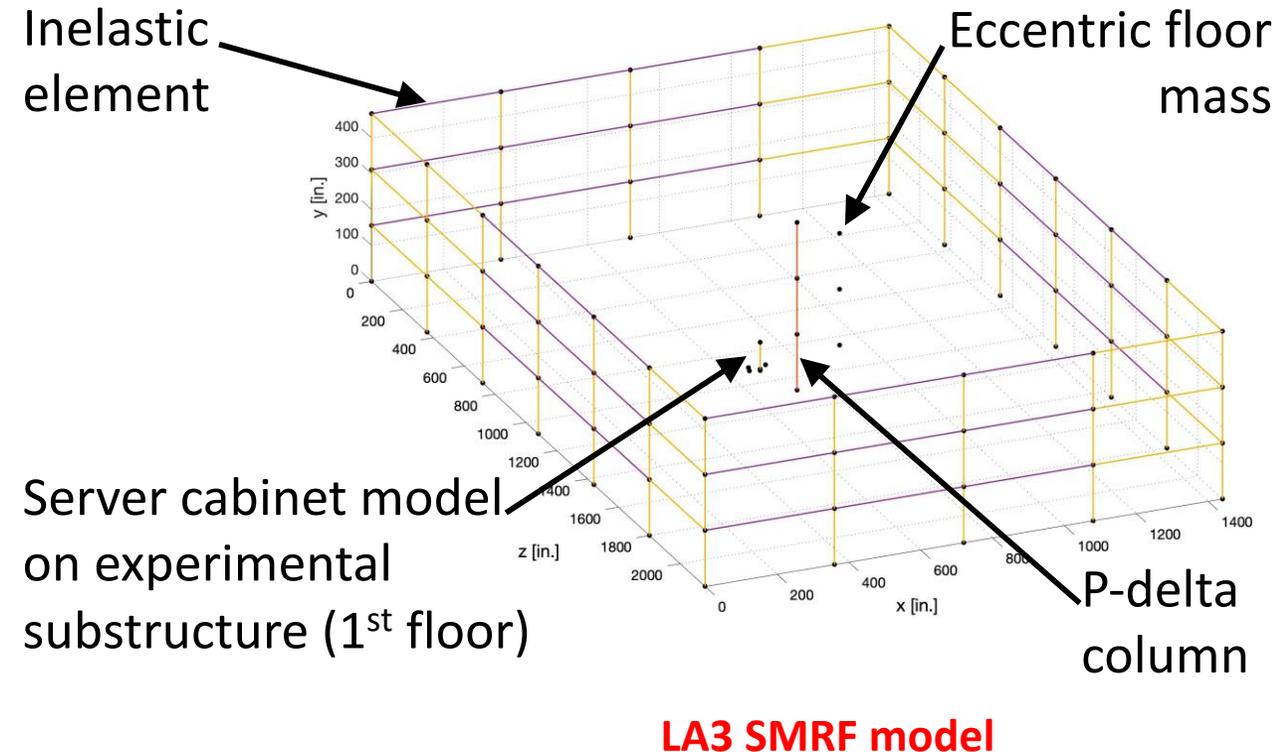
⁵ASCE, ASCE 7 Hazard Tool, Online, URL <https://asce7hazardtool.online/>, 2022.

⁶USGS, Unified Hazard Tool, Online, URL <https://earthquake.usgs.gov/hazards/interactive/>, 2022.

⁷PEER, NGA-West2–Shallow Crustal Earthquakes in Active Tectonic Regimes, Online, URL <https://peer.berkeley.edu/research/nga-west-2>, 2021.

Analytical substructure: SMRF model

- Steel 3-story (LA3) special moment resisting frame (SMRF)⁸
- Inelastic force-based fiber beam-column elements for SMRF's girders
- Elastic elements for remaining structural components
- Modeled in 3D, including P- Δ effects, using HyCOM-3D⁹

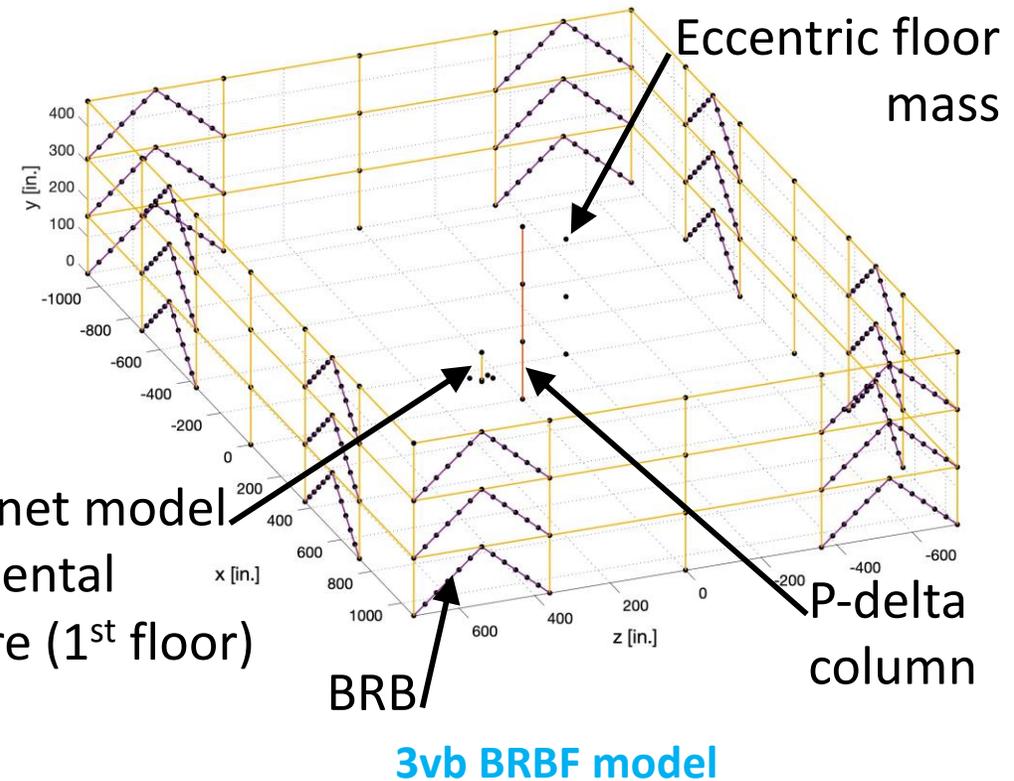


⁸SAC Joint Venture (2000), *State of the Art Report on Systems Performance of Steel Moment Frames Subject to Earthquake Ground Shaking*, Tech. Rep. FEMA-355C, Washington, DC.

⁹Ricles, J., Kolay, C., Marullo, T. M. (2021), *HyCoM-3D: A Program for 3D Nonlinear Dynamic Analysis and Real-Time Hybrid Simulation of 3-D Civil Infrastructure Systems*, Tech. Rep., Hybrid Computational Modeling (HyCoM) Program-3D Version 3.8 User's Manual, Lehigh University.

Analytical substructure: BRBF model

- Steel 3-story (3vb) buckling-restrained brace frame (BRBF)¹⁰
- 3D inelastic truss elements for the BRBs⁷
- Elastic elements for remaining structural components
- Modeled in 3D, including P- Δ effects, using HyCOM-3D¹¹

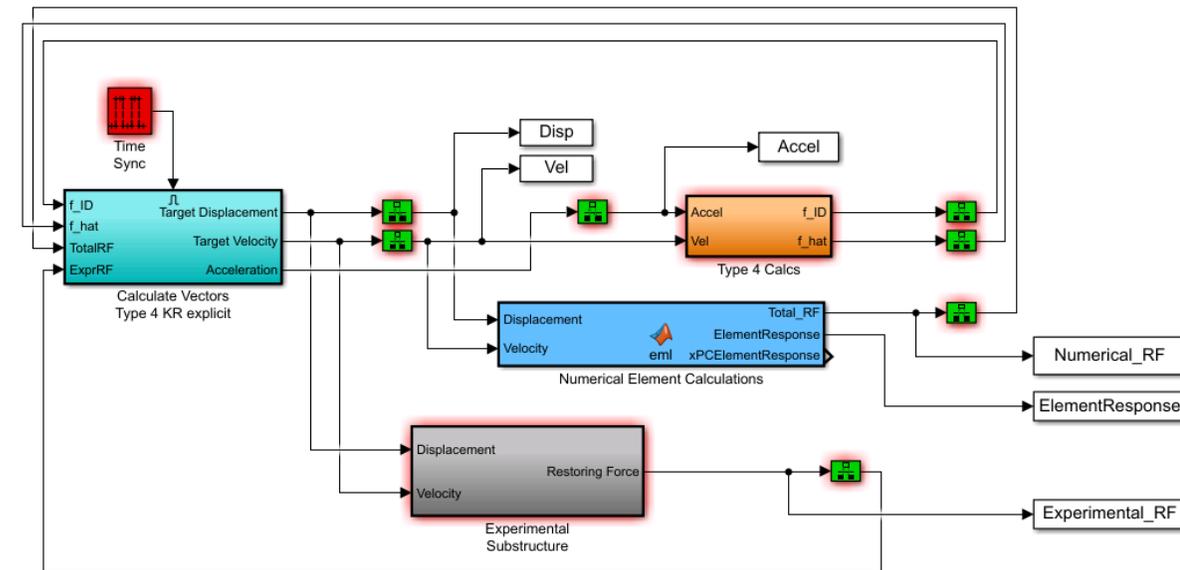


¹⁰Sabelli, R. (2001), *Research on Improving the Design and Analysis of Earthquake Resistant Steel Braced Frames*, Tech. Rep. PF2000-9, Earthquake Engineering Research Institute, Oakland, CA.

¹¹Kersting, R. et.al. (2015), *Seismic Design of Steel Buckling-Restrained Braced Frames: A guide for practicing engineers*, NEHRP Seismic Design Technical Brief No. 11, NIST GCR 15-917-34.

RTHS implementation

- MATLAB/Simulink¹² simulation coordinator interface
- Analytical substructure component modeled in customized RTHS software HyCOM-3D⁵, using explicit-formulated computational elements¹³
- MKR- α used as the integration algorithm (model-based, second-order accuracy, explicit unconditionally stable)^{14, 15}



Simulation coordinator of synchronized control & data acquisition in MATLAB/Simulink⁸

¹²MATLAB and Optimization Toolbox Release R2022a, The MathWorks, Inc., Natick, Massachusetts, United States

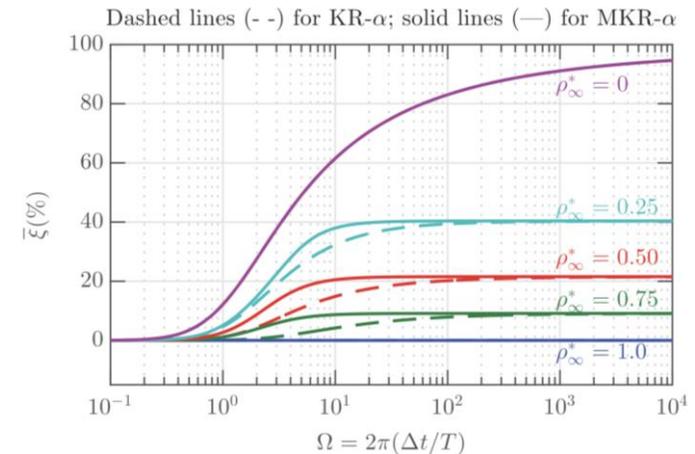
¹³Kolay, C. & Ricles, J.M. (2018), *Journal of Structural Engineering*. doi: 10.1061/(ASCE)ST.1943-541X.0001944.

¹⁴Kolay, C. & Ricles, J.M. (2014), *Earthquake Engng Struct Dyn*. doi: 10.1002/eqe.2401.

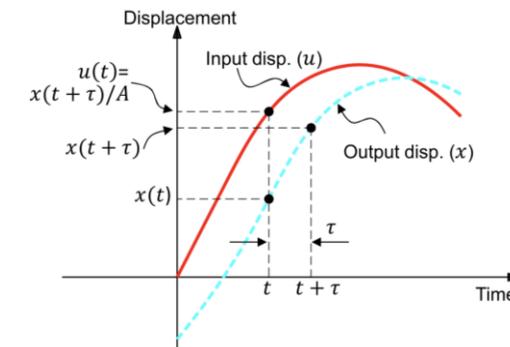
¹⁵Kolay, C. & Ricles, J.M. (2017), *Journal of Earthquake Engineering*. doi: 10.1080/13632469.2017.1326423.

RTHS implementation (cont.)

- To control numerical dissipation and overshoot, dissipative integration algorithm $\rho_{\infty}^* = 0.5$ ^{14, 15}
- The integration time step was established at 2/1024 s with 2-step interpolations
- Adaptive time series (ATS) compensator essential to actuator control ¹⁶



Variation of equivalent damping ratio with Ω for various values of ρ_{∞}^* ¹¹

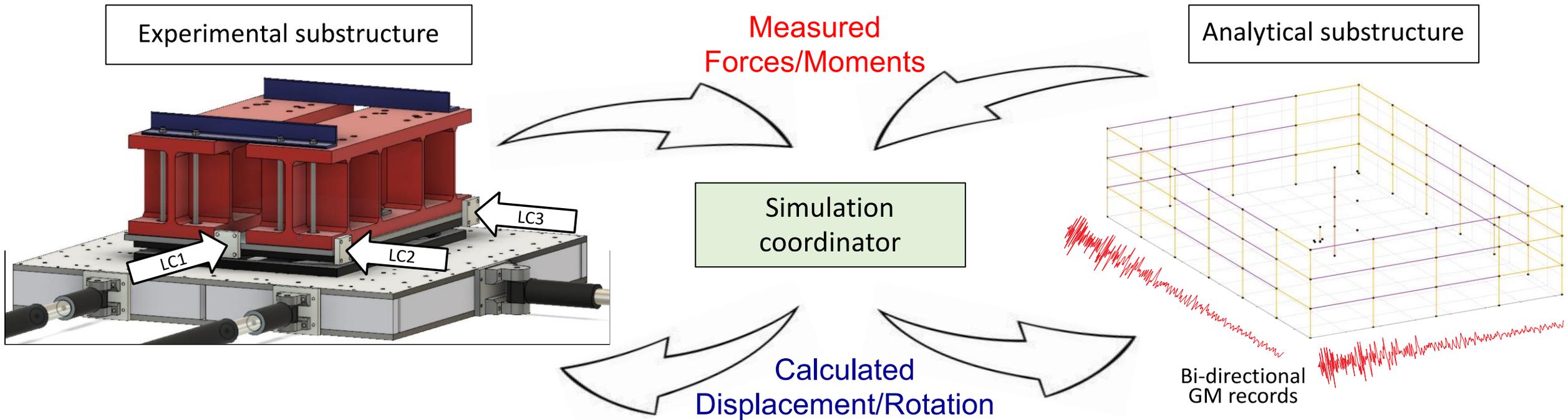


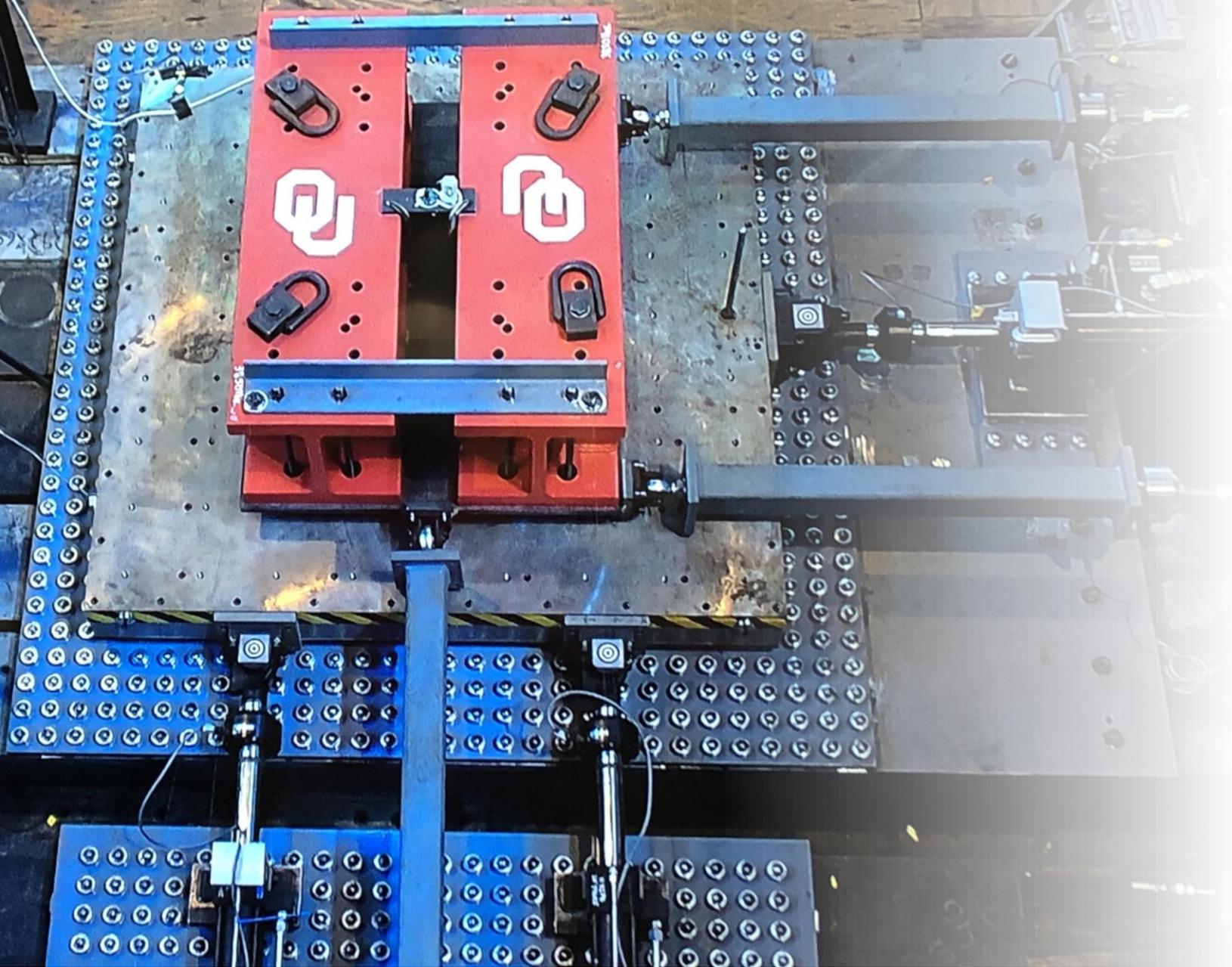
Input & output disp. servo-hyd. system with experimental substructure relationship ¹²

¹⁶Chae, Y., Kazemibidokhti, K., & Ricles, J.M. (2013), *Earthquake Engng Struct Dyn.* doi: 10.1002/eqe.2294.

RTHS implementation (cont.)

- Restraints are equipped with uniaxial load cells to obtain directly and in real-time the experimental restoring forces





Selected results

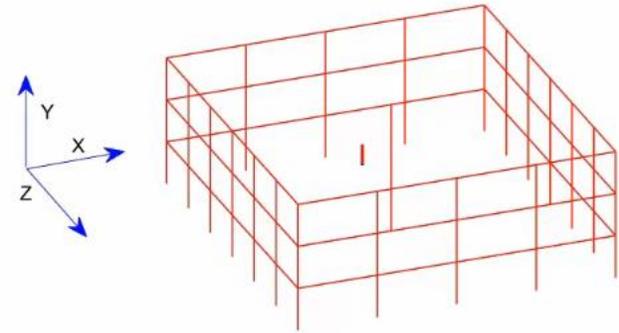


3-D Real-time Hybrid Simulation

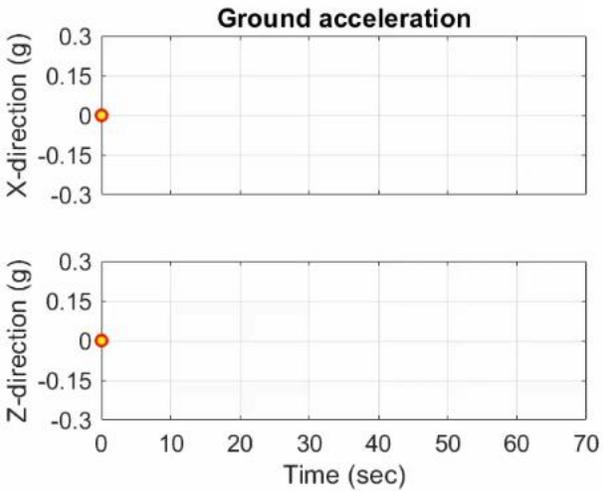
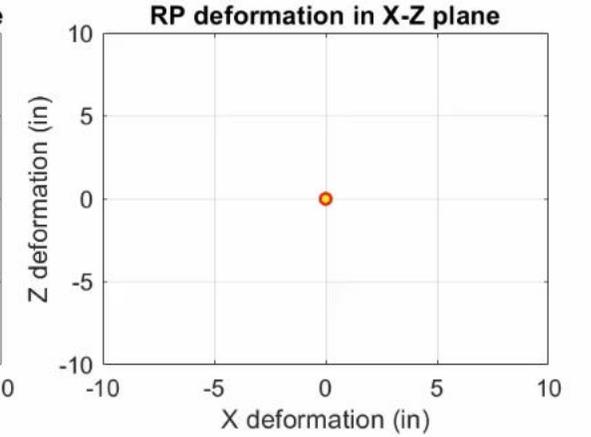
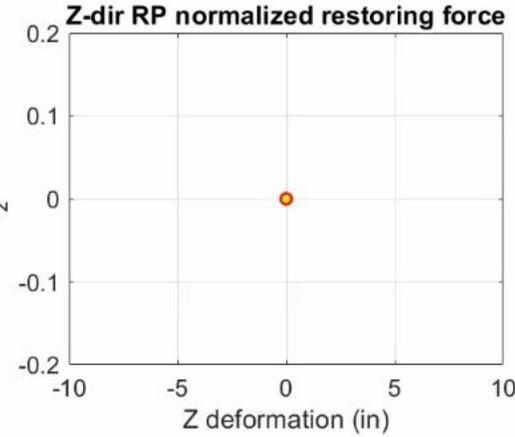
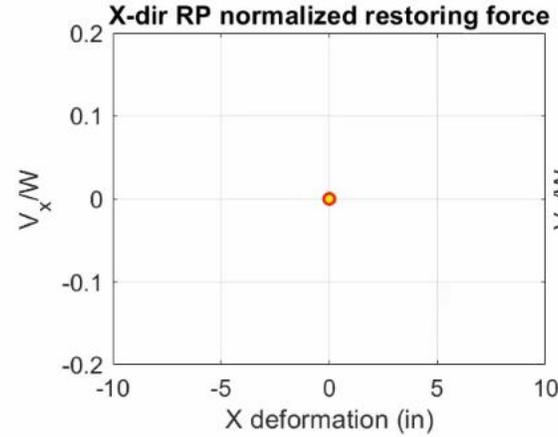
SMRF with RP Isolation System (FIS) @ 2nd Floor, Coalinga EQ Scaled to SLE

Analytical Substructure, Scale factor = 25

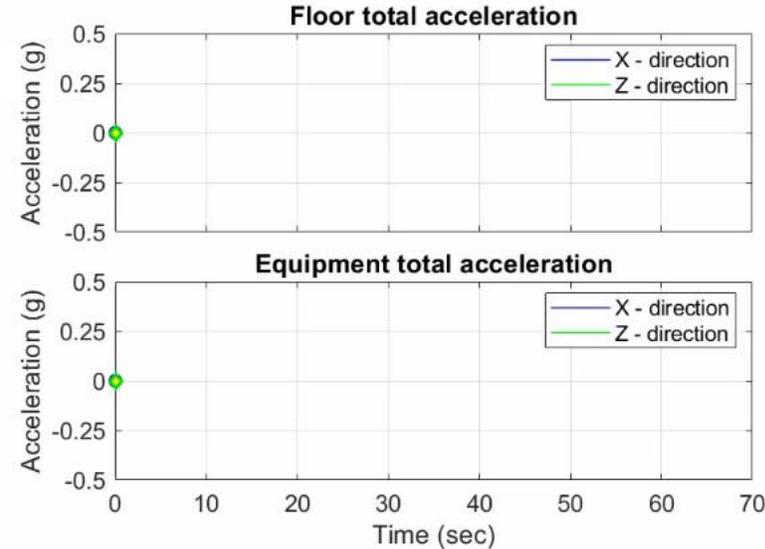
Time (sec.) = 0



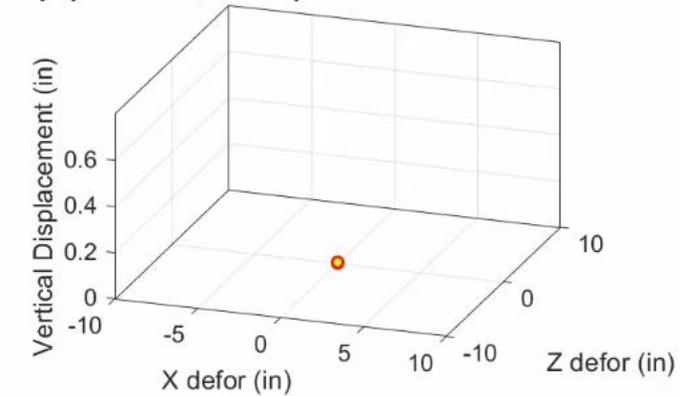
- Analytical Substructure (Building & Equipment)
- Experimental Substructure (FIS)



FIS - Experimental Substructure



Equipment vertical displacement vs RP deformation



X-direction = 270 component, Z-direction = 360 component

3-D Real-time Hybrid Simulation of a 3-Story SMRF with 2nd Floor Rolling Pendulum Equipment Isolation System: 1983 Coalinga EQ Bidirectional Ground Motions Recorded at Cantua Creek School and Scaled to SLE Hazard Level.

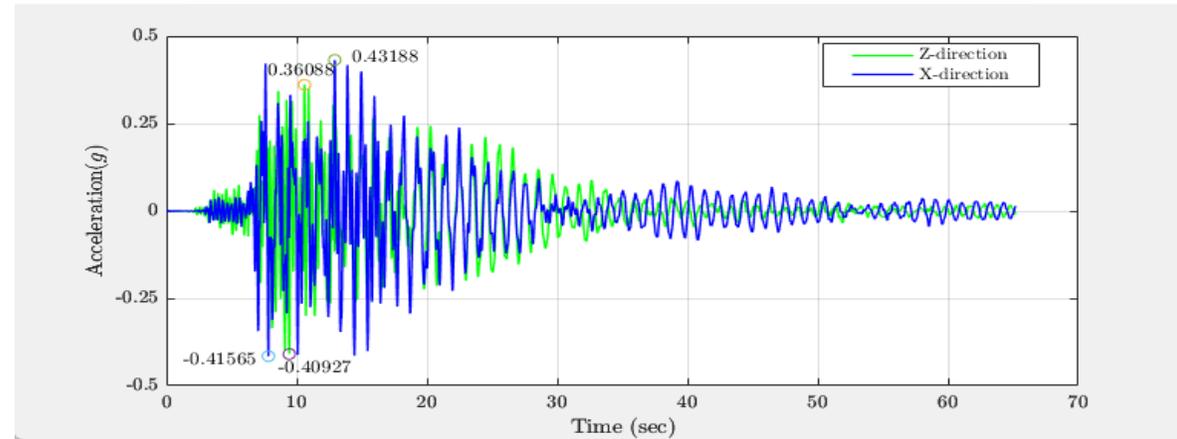
Equipment Acceleration

SMRF with RP Isolation System @ 2nd Floor

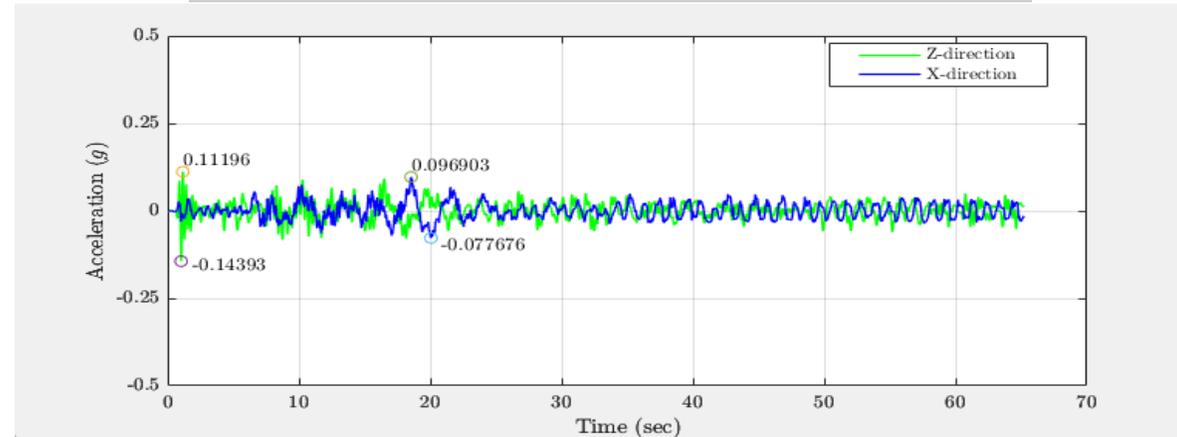
Reduction in Equipment Total Acceleration

X-Direction	Z-Direction
81.3%	68.9%

SMRF 2nd Floor Total Acceleration



Equipment Total Acceleration



Acknowledgements

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The authors would like to also thank WorkSafe Technologies, Inc. for providing the RP isolator units and the input on the typical operating conditions of these systems

The opinions expressed herein are those of the authors and do not necessarily reflect the views of the sponsors

